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# Nonlinear thermal instability in a horizontal porous layer with an internal heat source and mass flow

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Abstract Linear and nonlinear stability analyses of Hadley-Prats flow in a horizontal fluid-saturated porous medium with a heat source are studied. The results indicate that, in the linear case, an increase in the horizontal thermal Rayleigh number is stabilizing for both positive and negative values of mass flow. In the nonlinear case, a destabilizing effect is identified at higher mass flow rates. An increase in the heat source has a destabilizing effect. Qualitative changes appear in  $R_z$  as the mass flow moves from negative to positive for different internal heat sources.

Keywords Nonlinear stability analysis · Heat source · Porous medium · Mass flow

#### 1 Introduction

Thermal convection driven by an internal heat source with a horizontal mass flow has many practical applications such as underground energy transport, cooling of nuclear reactors, food processing, oil recovery, underground storage of waste products and thermal convection in clouds [1–4].

In the last few decades, convection involving internal heat sources has attracted particular research attention. Early experimental investigations include Schwiderski et al. [5] and Tritton et al. [6], with Roberts [7] and Thirlby [8] providing theoretical analyses. Parthiban and Patil [9] investigated thermal convection due to non-uniform heating boundaries with inclined thermal gradients in the presence of an internal heat source, followed by an extension to anisotropic porous layers by Parthiban and Patil [10]. The case of an inclined layer with internal heat source was analyzed by Barletta et al. [11], where both boundaries were isothermal and kept at the same temperatures. Rionero and Straughan [12] investigated the linear and nonlinear effects in the presence of variable gravity effect and heat generation. Extensive reviews of the theory and applications can be found in the article by Alex and Patil [13]. Hill [14] investigated a porous layer with concentration based internal heat generation, with linear and nonlinear stability analyses of thermosolutal convection. Chamka [15] analyzed the effect of an internal heat source or sink for hydromagnetic simultaneous heat and mass transfer by utilising similarity solutions. Thermosolutal convection in a saturated anisotropic porous medium with internal heat generation is reported by Bhadauria [16]. Borujerdi et. al [17] examined the steady state heat conduction with a uniform heat source where the solid and fluid phase are at different temperatures. Borujerdi et. al [18] study the influence of Darcy number on the critical Rayleigh number in onset of

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convection with uniform internal heating. A collection of comprehensive theories and experiments of thermal convection in porous media (with their practical applications), has been surveyed by Nield and Bejan [19]. Capone and Rionero [20] have studied the nonlinear stability analysis of a convective motion in a horizontal porous layer which is driven by a temperature gradient. Several problems on nonlinear stability analyses using the energy method are discussed by Kaloni and his contributors [21–25]. In the Lyapunov sense, when the disturbance of the basic flow is unstable linearized theory provide sufficient conditions, whereas nonlinear theory provides sufficient conditions for the disturbance to be asymptotically stable.

The aim of this article is to study the influences of both a heat source and a mass flow. The corresponding eigenvalue problems are solved numerically utilising the shooting and Runga-Kutta method.

#### 2 Mathematical analysis

An infinite shallow horizontal fluid saturated porous medium with thickness d is considered. The z'-axis is vertically upwards and there is a net flow along the direction of x'- axis with magnitude M'. The vertical temperature difference across the boundaries is  $\Delta\theta$ . Further imposed is the horizontal temperature gradient vector  $(\beta_{\theta_x}, \ \beta_{\theta_y})$ . The porous layer flow is governed by the Darcy law, where the linear Boussinesq approximation is assumed. Utilising the equation of the conservation of energy, the governing equations in dimensional form are

$$\nabla' \cdot q' = 0 \,, \tag{1}$$

$$\frac{\mu}{K}q' + \nabla'P' - \rho_0 \left[1 - \gamma_\theta \left(\theta' - \theta_0\right)\right]g = 0, \tag{2}$$

$$(\rho c)_{m} \left( \frac{\partial \theta'}{\partial t'} \right) + (\rho c_{p})_{f} q' \cdot \nabla' \theta' = k_{m} \nabla'^{2} \theta' + Q', \tag{3}$$

with the following boundary conditions:

$$w' = 0, \quad \theta' = \theta_0 - \frac{1}{2} (\pm \triangle \theta) - \beta_{\theta_x} x' - \beta_{\theta_y} y' \quad \text{at} \quad z' = \pm \frac{d}{2}.$$
 (4)

Here, the Darcy velocity is defined as q' = (u', v', w'), P' is the pressure,  $\theta'$  is temperature and Q' is an internal heat source. The subscripts f and m are refer to the fluid and the porous medium, respectively.  $\phi$  and K are the porosity and permeability of the porous layer. c,  $\rho$ ,  $\mu$ ,  $k_m$  and  $\gamma_\theta$  denote the specific heat, density, viscosity, thermal diffusivity, and thermal expansion coefficient in the porous medium, respectively.

The following dimensionless variables are introduced to non-dimensionalize the governing equations:

$$(x,y,z) = \frac{1}{d} \left( x^{'},y^{'},z^{'} \right), \hspace{0.5cm} t = \frac{\alpha_{m}t^{'}}{ad^{2}}, \hspace{0.5cm} q = \frac{dq^{'}}{\alpha_{m}}, \hspace{0.5cm} P = \frac{K \left( P^{'} + \rho_{0}gz^{'} \right)}{\mu\alpha_{m}}, \label{eq:equation:equatio:equation:equation:equation:equation:equation:equation:equation:$$

$$\theta = \frac{R_z \left(\theta' - \theta_0\right)}{\triangle \theta}, \quad M = \frac{dM'}{\alpha_m}, \quad Q = \frac{d^2 Q'}{k_m \triangle \theta}, \tag{5}$$

where

$$\alpha_m = \frac{k_m}{(\rho c_p)_f}, \quad a = \frac{(\rho c)_m}{(\rho c_p)_f}, \quad R_z = \frac{\rho_0 g \gamma_\theta K d \triangle \theta}{\mu \alpha_m}.$$
 (6)

Here,  $R_z$  denote the vertical thermal Rayleigh number. The horizontal thermal Rayleigh numbers are defined as follows

$$R_x = \frac{\rho_0 g \gamma_\theta K d^2 \beta_{\theta_x}}{\mu \alpha_m}, \quad R_y = \frac{\rho_0 g \gamma_\theta K d^2 \beta_{\theta_y}}{\mu \alpha_m}.$$
 (7)

The previous scaling for dimensional variables and the horizontal thermal Rayleigh numbers was introduced by Weber [27] and used extensively by Nield [28]. Under these dimensionless variables, the governing Eqs. (1) - (3) are

$$\nabla \cdot q = 0 , \qquad (8)$$

$$q + \nabla P - \theta \mathbf{k} = 0, \tag{9}$$

$$\frac{\partial \theta}{\partial t} + q \cdot \nabla \theta = \nabla^2 \theta + Q R_z, \tag{10}$$

with the conditions of the plates being

$$w = 0, \quad \theta = -\frac{1}{2} (\pm R_z) - R_x x - R_y y \quad \text{at} \quad z = \pm \frac{1}{2}.$$
 (11)

From Eqs. (8) - (10) we observe that all of the thermal Rayleigh numbers are involved in boundary conditions (11). The condition on temperature at both bounding planes give a linear variation of temperature. This spatial linear variation on temperature along the horizontal planes bounding a fluid layer is a physically more realistic situation than the strictly uniform heating Capone and Rionero [20]. However, in the present problem uniform heating can be recovered by setting the horizontal thermal gradients to zero.

#### 3 Steady-state Solution

The flow governing equations (8)-(10), subject to (11), has a basic state solution of the form

$$\theta_s = \widetilde{\theta}(z) - R_x x - R_y y,$$

$$u_s = u(z), \quad v_s = v(z), \quad w_s = 0, \quad P_s = P(x, y, z),$$
 (12)

with

$$u_s = -\frac{\partial P}{\partial x}, \quad v_s = -\frac{\partial P}{\partial y},$$

$$0 = -\frac{\partial P}{\partial z} + \widetilde{\theta}(z) - R_x x - R_y y,$$

$$D^2\widetilde{\theta} = -u_s R_x - v_s R_y - Q R_z. \tag{13}$$

Here  $D = \frac{d}{dz}$ , and we have a net flow M in the horizontal direction such that  $\int_{-1/2}^{1/2} u(z)dz = M$  and  $\int_{-1/2}^{1/2} v(z)dz = 0$ . The solution in the form of flow velocity and temperature in the medium is then given by

$$u_s = R_x z + M, \quad v_s = R_y z, \tag{14}$$

$$\widetilde{\theta} = -R_z z - \frac{\lambda}{24} \left( 4z^3 - z \right) - \left( MR_x + QR_z \right) \left( \frac{z^2}{2} - \frac{1}{8} \right), \tag{15}$$

where  $\lambda = R_x^2 + R_y^2$ .

### 4 Perturbation Equations

We consider the perturbations in the form  $q = q_s + \overline{q}$ ,  $\theta = \theta_s + \overline{\theta}$  and  $P = P_s + \overline{P}$ . By substituting these perturbations in the dimensionless governing equations (8) - (10), we get

$$\nabla \cdot \overline{q} = 0 \,, \tag{16}$$

$$\overline{q} = -\nabla \overline{P} + \overline{\theta} \mathbf{k},\tag{17}$$

$$\frac{\partial \overline{\theta}}{\partial t} + q_s \cdot \nabla \overline{\theta} + \overline{q} \cdot \nabla \theta_s + \overline{q} \cdot \nabla \overline{\theta} = \nabla^2 \overline{\theta}, \tag{18}$$

where

$$\nabla \theta_s = -\left(R_x, R_y, R_z - \widetilde{A}\right).$$

$$\widetilde{A} = \frac{\lambda}{24} \left[ 1 - 12z^2 \right] - \left( MR_x + QR_z \right) z,$$

The conditions at the plates are

$$\overline{w} = 0, \quad \overline{\theta} = 0 \quad \text{at} \quad z = \pm \frac{1}{2}.$$
 (19)

Note that (19) shows that there are no normal velocity and temperature perturbations at the plates.

## 5 Linear Stability Analysis

To perform a linear stability analysis we neglect the nonlinear terms from Eq. (18). The linearized perturbations equations are then

$$\nabla \cdot \overline{q} = 0, \tag{20}$$

$$\overline{q} = -\nabla \overline{P} + \overline{\theta} \mathbf{k},\tag{21}$$

$$\frac{\partial \overline{\theta}}{\partial t} + q_s \cdot \nabla \overline{\theta} + \overline{q} \cdot \nabla \theta_s = \nabla^2 \overline{\theta} , \qquad (22)$$

where

$$\nabla\theta_{s}=-\left(R_{x},R_{y},R_{z}-\frac{\lambda}{24}\left[1-12z^{2}\right]+\left(MR_{x}+QR_{z}\right)z\right).$$

The conditions at the plates are

$$\overline{w} = 0, \quad \overline{\theta} = 0 \quad \text{at} \quad z = \pm \frac{1}{2} \ .$$
 (23)

Adopting a normal mode solution to Eqs. (20) - (22) of the form

$$\left[\overline{q}, \overline{\theta}, \overline{P}\right] = \left[q\left(z\right), \theta\left(z\right), P\left(z\right)\right] \exp\left\{i\left(kx + ly\right) + \sigma t\right\} \tag{24}$$

and further eliminating P, yields

$$(D^2 - \alpha^2) w + \alpha^2 \theta = 0, \tag{25}$$

$$\left(D^2 - \alpha^2 - (\sigma + i(ku_s + lv_s))\right)\theta + \frac{i}{\alpha^2}(kR_x + lR_y)Dw - \left(D\widetilde{\theta}\right)w = 0.$$
 (26)

Eqs. (25) - (26), subject to  $w=\theta=0$  at both the plates  $z=\frac{1}{2}$  and  $z=-\frac{1}{2}$ , constitute an eigenvalue problem for vertical thermal Rayleigh number  $R_z$  with  $a,R_x,R_y,k$  and l as parameters. In the above,  $\alpha=\sqrt{k^2+l^2}$  is the overall wave number. Numerical results are presented in Section 7.

### 6 Nonlinear Stability Analysis

In this section our nonlinear analysis via energy functional is presented as follows. We multiply equations (17) and (18) by  $\overline{q}$  and  $\overline{\theta}$ , respectively, and integrate over  $\Omega$ , where  $\Omega$  denotes a typical periodicity cell. This yields the following identities

$$||\overline{q}||^2 = \langle \overline{\theta}\overline{w}\rangle, \tag{27}$$

$$\frac{1}{2} \frac{d||\overline{\theta}||^2}{dt} = -\langle (\overline{q} \cdot \nabla \theta_s) \overline{\theta} \rangle - ||\nabla \overline{\theta}||^2. \tag{28}$$

Here  $||\cdot||$  and  $\langle \cdot \rangle$  denote the norm and inner product on  $L^2(\Omega)$ . We adopt the energy functional (cf. [29])

$$E(t) = \frac{\xi}{2} \parallel \overline{\theta} \parallel^2 \tag{29}$$

with coupling parameter  $\xi > 0$ . The system of equations (27)-(28) along with Eq. (29), can now be represented in the form

$$\frac{dE}{dt} = I - \Delta,\tag{30}$$

where

$$I = -\xi \langle (\overline{q} \cdot \nabla \theta_s) \, \overline{\theta} \rangle + \langle \overline{\theta} \overline{w} \rangle, \tag{31}$$

$$\Delta = \xi ||\nabla \overline{\theta}||^2 + ||\overline{q}||^2. \tag{32}$$

We define

$$n = \max_{H} \frac{I}{\Lambda} \tag{33}$$

where H is the space of all admissible solutions to equations (16) - (18). If 0 < n < 1 it follows that

$$\frac{dE}{dt} \le -\Delta \left(1 - n\right). \tag{34}$$

The classical Poincare inequality  $||\overline{q} - \overline{q}_{\Omega}||_{L^{p}(\Omega)} \leq C||\nabla \overline{q}||_{L^{p}(\Omega)}$ , where  $\Omega$  is a open connected locally compact Hausdorff space and use of  $\overline{q}_{\Omega} = \frac{1}{|\Omega|} \int_{\Omega} \overline{q}(y) \, dy$  yields

$$\frac{dE}{dt} \le -2\pi^2 (1 - n) \min\{1, \frac{a}{L_e \phi}\}E. \tag{35}$$

Eq. (35) then guarantees that  $E(t) \to 0$  as  $t \to \infty$  for 0 < n < 1. Applying the arithmetic-geometric mean inequality on Eq. (27) yields

$$||\overline{q}||^2 \le ||\overline{\theta}||^2. \tag{36}$$

From Eqs. (36) and (29) it follows that the decay of  $||\overline{q}||$  is implied by the decay of E(t) and hence the system is stable. From the above, we have identified that the non-linear stability requires the critical argument at n = 1. The corresponding Euler-Lagrange system with the maximum problem Eq. (33) is

$$\xi \overline{\theta} \nabla \theta_s - \overline{\theta} \mathbf{k} + 2 \overline{q} = \nabla \overline{\delta}, \tag{37}$$

$$\overline{w} - \xi \overline{q} \cdot \nabla \theta_s + 2\xi \nabla^2 \overline{\theta} = 0. \tag{38}$$

Here  $\bar{\delta}$  is Lagrange multiplier introduced because  $\bar{q}$  is divergence free. We consider  $R_z$  as the eigenvalue and estimate the maximum variation of  $R_z$  with optimal choice of  $\xi$ . Eqs. (37) - (38) yield

$$\frac{\partial R_z}{\partial \xi} = \frac{n \left(1 - \xi R_z\right) ||\nabla \overline{\theta}||^2 + \langle \widetilde{A} \overline{\theta} \overline{w} \rangle - R_x \langle \overline{\theta} \overline{u} \rangle + R_y \langle \overline{\theta} \overline{v} \rangle}{\xi^2 \left(2n||\nabla \overline{\theta}||^2 + \langle \widetilde{A} \overline{\theta} \overline{w} \rangle - R_x \langle \overline{\theta} \overline{u} \rangle + R_y \langle \overline{\theta} \overline{v} \rangle\right)},$$
(39)

Equation (39) is important, and also noted that if  $R_x = R_y = 0$  and Q = 0, we get

$$\frac{\partial R_z}{\partial \xi} = \frac{(1 - \xi R_z)}{2\xi^2}.\tag{40}$$

Equation (40) is same as the expressions reported by Guo and Kaloni [21]. We solve the system of Eqs. (37) - (38) in presence of critical value n = 1. To evaluate this system numerically, we apply *curlcurl* of Eq. (37) and further use the third component of the resulting equation

$$\xi R_x \frac{\partial^2 \overline{\theta}}{\partial x \partial z} + \xi R_y \frac{\partial^2 \overline{\theta}}{\partial u \partial z} + \xi \nabla_1^2 \left[ \left( -R_z + \widetilde{A} \right) \overline{\theta} \right] + 2 \nabla_1^2 \overline{w} - \nabla_1^2 \overline{\theta} - 2 \left( \frac{\partial^2 \overline{u}}{\partial x \partial z} + \frac{\partial^2 \overline{v}}{\partial u \partial z} \right) = 0, \tag{41}$$

where  $\nabla_1^2 = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2}\right)$ . Now, we apply the normal mode expansion

$$\left[\overline{q}, \overline{\theta}, \overline{\delta}\right] = \left[q(z), \theta(z), \delta(z)\right] \exp\left(i(kx + ly)\right), \tag{42}$$

with  $(R_x, R_y) \cdot (k, l) = 0$ , (Nield [26] and Kaloni and Qiao [22]), i.e the horizontal thermal Rayleigh number vector is orthogonal to wave number vector. We substitute (42) in Eqs. (37), (38), (41) and eliminate u, v and  $\delta$  to obtain

$$D^{2}w = \frac{\alpha^{2}}{2} \left( 2w + \xi \left[ -R_{z} + \widetilde{A} \right] \theta - \theta \right), \tag{43}$$

$$D^{2}\theta = \frac{1}{2} \left[ -R_{z} + \widetilde{A} - \xi^{-1} \right] w + \left[ \alpha^{2} - \xi \left( \frac{R_{x}^{2} + R_{y}^{2}}{4} \right) \right] \theta.$$
 (44)

The system of Eqs. (43) to (44) is evaluated with the boundary conditions  $w = \theta = 0$  at  $z = \pm \frac{1}{2}$ . The critical vertical thermal Rayleigh number is obtained as  $R_z = \max_{\xi} \min_{\alpha^2} R_z$ .

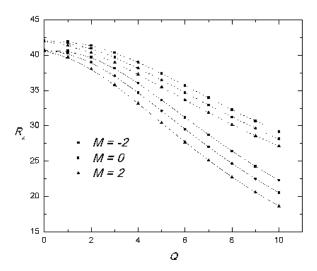
#### 7 Results and Discussion

The onset of thermal convection in a fluid-saturated porous layer in the presence of mass flow and an internal heat source effect is analyzed using both linear and nonlinear stability theory. Both cases are studied based on the classical normal mode technique. We treat the vertical thermal Rayleigh number as the eigenvalue  $R_z$ . Here, the critical vertical thermal Rayleigh number  $R_z$  is defined as the minimum of all  $R_z$  values as the wave number  $\alpha$  is varied. The vector of wave number is defined as  $\alpha = (k, l, 0)$ . To achieve the stationary convection boundary, we set  $\sigma = 0$  (the removal of the oscillatory mode is discussed in the Appendix), with  $(R_x, R_y) \cdot (k, l) = 0$ . The term longitudinal disturbances are characterized by k = 0. In the same way, transverse disturbances are characterized by l = 0. In Table 1,  $R_{z_l}$  and  $R_{z_e}$  indicate the linear and nonlinear critical thermal Rayleigh number  $(R_z)$ .  $\alpha_l$  and  $\alpha_e$  indicate the critical wave number in linear and nonlinear cases. From Table 1, it is observed that when

**Table 1** Critical thermal Rayleigh numbers at M=0.

	$R_x$	0	10	20	30	40
Q = 0	$R_{z_l}$	39.4784	42.0076	49.5486	61.9566	78.9663
	$\alpha_l$	3.13999	3.1399	3.1499	3.1599	3.2199
	$R_{z_e}$	39.47840	40.72345	44.20928	49.18550	53.61943
	$\alpha_e$	3.13999	3.08999	2.94999	2.7199	2.2799
Q = 1	$R_{z_{I}}$	39.2360	41.7294	49.1460	61.2757	77.7028
	$\alpha_l$	3.1599	3.1599	3.1699	3.2099	3.3099
	$R_{z_e}$	39.05626	40.27496	43.67935	48.51113	52.6681
	$\alpha_e$	3.15999	3.109999	2.96999	2.73999	2.28999
Q=2	$R_{z_i}$	38.53950	40.93195	47.99451	59.34272	74.11823
	$\alpha_l$	3.19999	3.19999	3.22999	3.33999	3.59999
	$R_{z_e}$	37.85142	38.99556	42.16919	46.59001	49.8985
	$\alpha_e$	3.20999	3.15999	3.0299	2.7999	2.27999

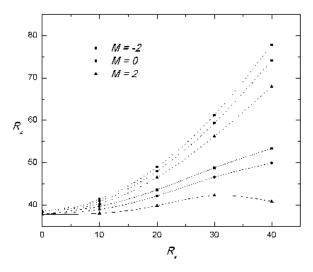
Q=0 and M=0, in the linear case, the results are in very good agreement with earlier published results in the literature, Nield [26]. For an increase in the value of Q from 0 to 2, the critical value of  $R_z$  is reduced seen in Table 1 in both cases. Hence, the heat flow parameter causes destabilization in the medium. A fixed notation is used to represent the curves corresponding to the linear and non-linear results. Dotted lines represent linear stability results and solid lines represents nonlinear stability results in Figs. 1 to 3.



**Fig. 1** Variation of  $R_z$  with Q at  $R_x = 10$  and  $R_y = 0$ .

A comparison of the critical value of  $R_z$  as a function of Q for different values of the mass flow rate M is shown in Fig. 1 at  $R_x = 10$  and  $R_y = 0$ . It is observed that, as Q increases the critical values of  $R_z$  decreases. However, as M increases from -2 to 2, at a higher value of M, the critical  $R_z$  value is lower than at lower values of M in both the cases as seen in Fig. 1. For both positive and negative values of M,  $R_z$  decreases with increasing values of Q. It indicates that increasing the heat source has a strongly destabilizing effect. This is due to the fact that the global temperature of the system is increasing with increasing heat source and causes the instability. As increasing the heat source the threshold critical region between linear and nonlinear results is increasing as seen in Fig. 1.

The response of  $R_z$  with varying  $R_x$  is shown in Fig. 2 for negative and positive values of M.

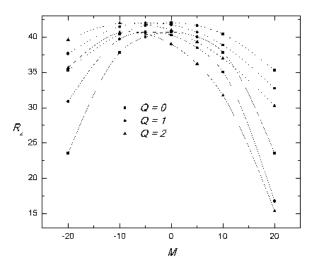


**Fig. 2** Variation of  $R_z$  with  $R_x$  at Q=1 and  $R_y=0$ .

It is noted that, at M=-2 in the linear case, the critical value of  $R_z$  is higher than the remaining all values of M. When  $R_x$  is increased the corresponding  $R_z$  values also increase for all M values. This indicates that the flow rate is strongly stabilizing in the linear case as compared to nonlinear case seen in Fig. 2. It is also interesting to observe that, as  $R_x$  increases the critical value of  $R_z$  also increases up

to certain value of  $R_x$  thereafter the  $R_z$  value decreases for M=2 in nonlinear case seen in Fig. 2. It means that, the flow rate is strongly destabilizing at higher values of  $R_x$  and M in the nonlinear case.

Fig. 3 shows the response of  $R_z$  with mass flow rate M in the presence of different values of Q = 0, 1, 2 for  $R_x = 10$ .



**Fig. 3** Variation of  $R_z$  with M at  $R_x = 10$  and  $R_y = 0$ .

As mass flow rate (M) increases  $R_z$  also increases up to certain values of M thereafter decreases for all values of Q as demonstarted in Fig. 3. Q has a strongly stabilizing effect up to certain value of M, then after strongly destabilizes the flow in both cases. It is seen that, increasing the magnitude of horizontal mass flow in both negative and positive directions, the critical value of  $R_z$  is decreased.

# 8 Conclusion

We have analyzed the instability of thermal convection in Hadley-Prats flow subject to an internal heat source using linear and nonlinear stability analysis. The results yield the following conclusions:

- An increase in the internal heat source causes a strong destabilization in all cases, as it raises the global temperature of the system.
- In the presence of horizontal mass flow, the flow is stabilizing at higher horizontal Rayleigh numbers in the linear case whereas it is destabilizing in the nonlinear case at larger mass flows.
- Qualitative changes appear in  $R_z$  as the mass flow moves from negative to positive for different internal heat sources.

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# Appendix

In this section we show that the imaginary part of  $\sigma$  is 0 (i.e. the oscillatory mode does not exist). After we use the condition  $(R_x, R_y) \cdot (k, l) = 0$ , Eqs. (25) - (26) transformed as

$$(D^2 - \alpha^2) w + \alpha^2 \theta = 0, \tag{45}$$

$$(D^{2} - \alpha^{2} - \sigma - iMk)\theta - (D\widetilde{\theta})w = 0,$$
(46)

subject to boundary conditions  $w = \theta = 0$  at both the plates  $z = \frac{1}{2}$  and  $z = -\frac{1}{2}$ . By eliminating  $\theta$ , for a single equation obtained from Eqs. (45) - (46) yields

$$(D^{2} - \alpha^{2})^{2} w - (\sigma + iMk) (D^{2} - \alpha^{2}) w + \alpha^{2} (D\widetilde{\theta}) w = 0.$$

$$(47)$$

Multiplying Eq. (47) by  $\overline{w}$  (complex conjugate of w) and integrating by parts over  $\left[-\frac{1}{2}, \frac{1}{2}\right]$ , and using the boundary condition we obtain

$$||D^{2}w||^{2} + 2\alpha^{2}||Dw||^{2} + \alpha^{4}||w||^{2} + (\sigma + iMk)\left(||Dw||^{2} + \alpha^{2}||w||^{2}\right) + \alpha^{2}\int_{-0.5}^{0.5} \left(D\widetilde{\theta}\right)|w|^{2} dz = 0.$$
 (48)

Taking the imaginary part of Eq. (48) when  $\sigma = \sigma_r + i\sigma_i$ 

$$\sigma_i(||Dw||^2 + \alpha^2||w||^2) = -Mk(||Dw||^2 + \alpha^2||w||^2). \tag{49}$$

When k = 0, we have  $\sigma_i(||Dw||^2 + \alpha^2||w||^2) = 0$ , implies  $\sigma_i = 0$ .

This shows that the stationary longitudinal mode is the only possible mode for the convection induced by horizontal mass flow as stated by Nield and Bejan [19] and Kaloni and Qiao [22].

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